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C

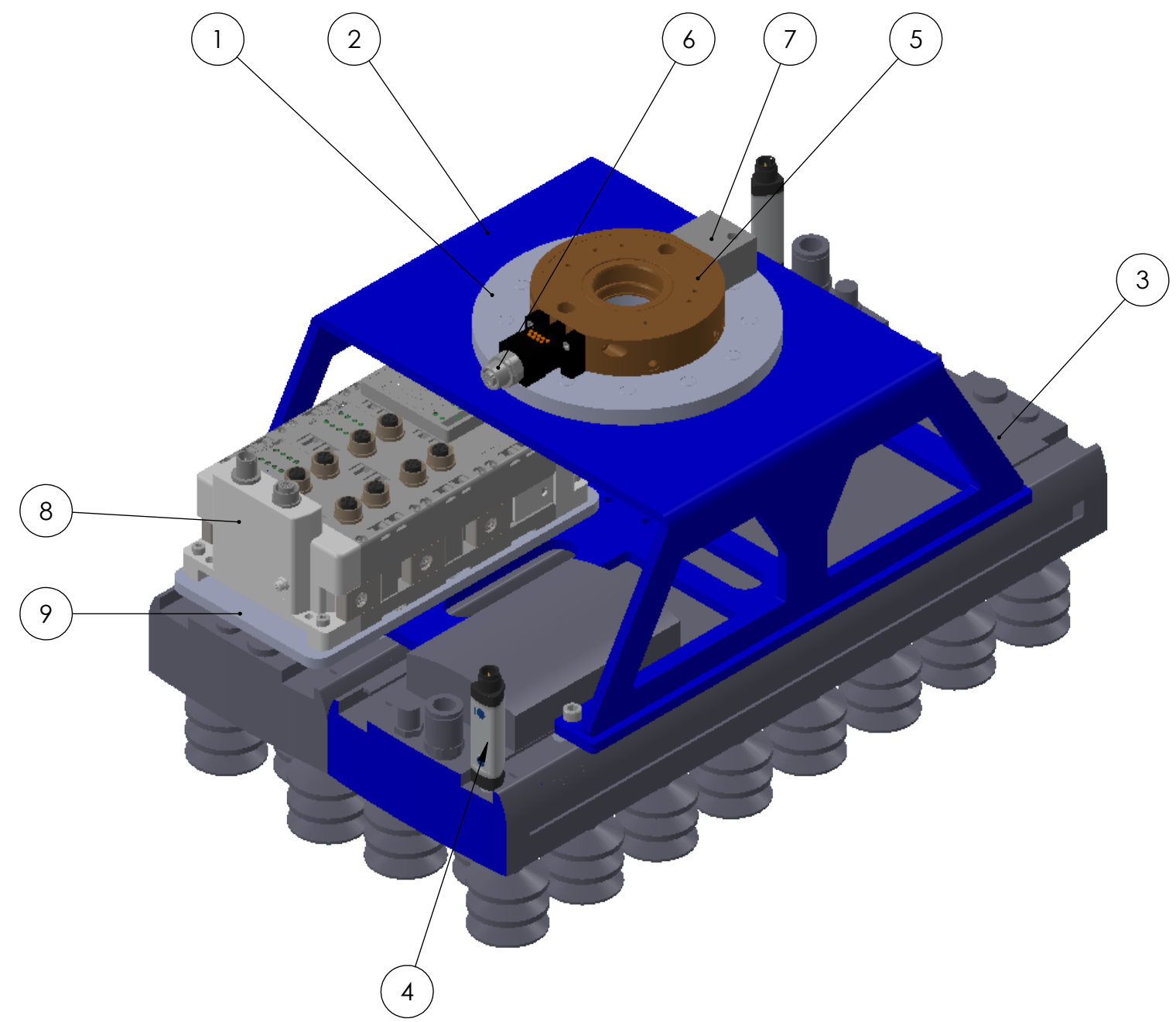
C

B

B

A

A



ITEM NO.	Mfg	Mfg Part Number	DESCRIPTION	QTY.
1	Ready	R-301523	Area Gripper to Robot Mount	1
2	N/A	N/A	Area Gripper Mounting Plate	1
3	N/A	N/A	Vacuum Gripping System	2
4	N/A	N/A	Air Sensor	2
5	N/A	N/A	Pneumatic Tool Changer	1
6	N/A	N/A	Tool Changer Electrical Pass-through	1
7	N/A	N/A	Tool Changer Pneumatic Pass-through	1
8	N/A	N/A	Communications Module	1
9	Ready	R-301530	Communications Module Mounting Plate	1
	McMaster	91292A215	M10 x 16mm	12
	McMaster	92125A282	M8 x 16mm, Flat Head	6
	McMaster	5537T761	M6, T-Nut	8
	McMaster	92125A240	M6 x 20mm, Flat Head	2
	McMaster	91292A134	M6 x 12mm	6
	McMaster	91292A043	M4 x 18mm	4

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DRAWN	NAME	DATE
ENG APPR.	Josh Miller	2021-08-05
COMMENTS		
Refer to file Schmalz EOAT		
for all geometry		

READY ROBOTICS

PART NO. R-700031

DESCRIPTION Schmalz EOAT

REV **A**

SHEET 1 OF 1 SHEET SIZE: B

6

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